

Image Quality Assessment for Photo-consistency Evaluation on Planar Classification in Urban Scenes

M.-A. Bauda^{1,2}, S. Chambon¹, P. Gurdjos¹ and V. Charvillat¹

¹ University of Toulouse, IRIT - INP - ENSEEIHT

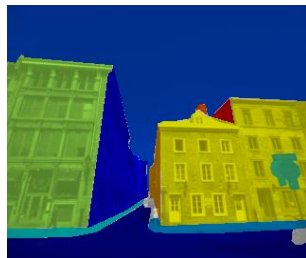
² imajing sas

ICPRAM 2015

Context



Set of calibrated images



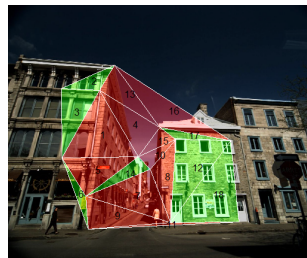
Semantic ground truth

Main goal - Semantic segmentation

Context



Set of calibrated images



Flatness ground truth

Main goal - Semantic segmentation

Paper issue - Relation between surface flatness and photo-consistency measure

Intermediate Features



Intermediate features

Aim - SuperPixels (SP)
photometrically coherent on
multiview

Intermediate Features



Intermediate features

Aim - SuperPixels (SP)
photometrically coherent on
multiview

Intermediate goal - Planar
classification for triangular mesh
(P/NP)

Intermediate Features



Intermediate features

Aim - SuperPixels (SP)
photometrically coherent on
multiview

Intermediate goal - Planar
classification for triangular mesh
(P/NP)

Idea

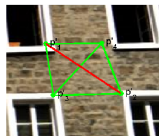
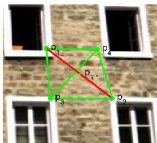
Integration of the geometrical
information in SP constructor

Photo-consistency Measure for P/NP Classification

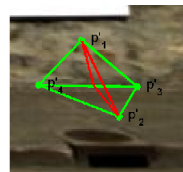
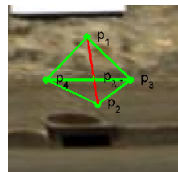
- **Inputs** - Calibrated multiview images and sparse 3D point cloud
- **Hypothesis** - Piecewise planar smooth surfaces
- **Tools** -
 - Homography estimation
 - Photo-consistency

Photo-consistency Measure for P/NP Classification

- **Inputs** - Calibrated multiview images and sparse 3D point cloud
- **Hypothesis** - Piecewise planar smooth surfaces
- **Tools** -
 - Homography estimation
 - Photo-consistency



Planar case - high similarity



Non-planar case - low similarity

Table of contents

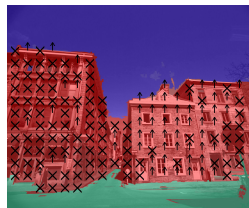
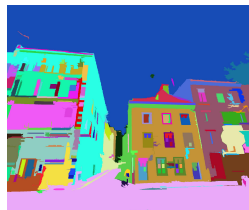
- 1 State-of-the-Art
- 2 Photo-Consistency Measures
- 3 IQA Evaluation Protocol
- 4 Overview

Table of contents

- 1 State-of-the-Art
- 2 Photo-Consistency Measures
- 3 IQA Evaluation Protocol
- 4 Overview

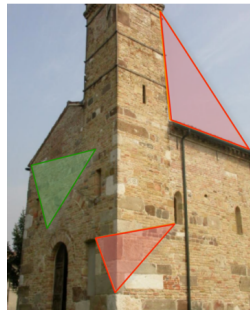
State-of-the-Art

- Single view approaches
 - SP over-segmentation method
[Felzenszwalb and Huttenlocher, 2004]
 - Geometry as a prior knowledge
[Hoiem et al., 2008]



State-of-the-Art

- Multiview approaches
 - Piecewise planar assumption
[Gallup et al., 2010]
 - Photo-consistency constraint
[Toldo and Fusiello, 2010]



Motivations

- Intermediate features
- Geometry and planar surfaces
- Photo-consistency

⇒ Evaluation protocol for photo-consistency measures

Table of contents

- 1 State-of-the-Art
- 2 Photo-Consistency Measures**
- 3 IQA Evaluation Protocol
- 4 Overview

Photo-Consistency Measures

Definition

Photo-Consistency Measure or **Image Quality Assessment (IQA)** quantification of photometrical similarity between a reference region z and a target region \tilde{z}

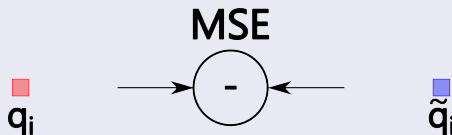
Analysis of two types of measures:

- Euclidean Distance-based Measures
- Cosine Angle Distance-based Measures

Euclidean Distance-based Measures

- N number of pixels in \mathbf{z} and $\tilde{\mathbf{z}}$
- v_i color value of the pixel q_i in the reference image
- \tilde{v}_i color value of the pixel \tilde{q}_i in the warped image
- r size of the neighbourhood used

Mean Square Error

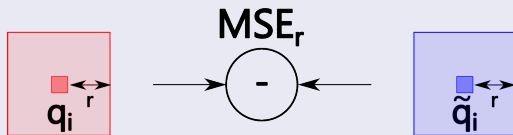


$$\text{MSE}(\mathbf{z}, \tilde{\mathbf{z}}) = \frac{1}{N} \sum_i (v_i - \tilde{v}_i)^2$$

Euclidean Distance-based Measures

- N number of pixels in \mathbf{z} and $\tilde{\mathbf{z}}$
- v_i color value of the pixel q_i in the reference image
- \tilde{v}_i color value of the pixel \tilde{q}_i in the warped image
- r size of the neighbourhood used

Generalised MSE

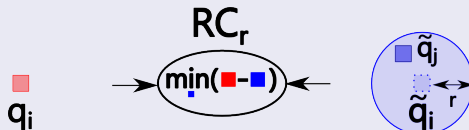


$$MSE_r(\mathbf{z}, \tilde{\mathbf{z}}) = \frac{1}{N} \sum_i \left[\frac{1}{(2r)^2} \sum_{j \mid |q_i - q_j| \leq r} (v_j - \tilde{v}_j)^2 \right]$$

Euclidean Distance-based Measures

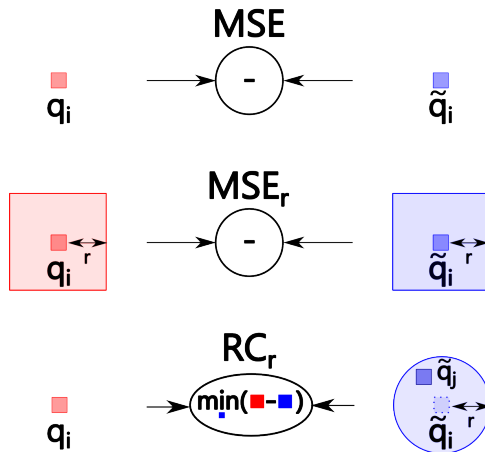
- N number of pixels in z and \tilde{z}
- v_i color value of the pixel q_i in the reference image
- \tilde{v}_i color value of the pixel \tilde{q}_i in the warped image
- r size of the neighbourhood used

r-Consistency [Kutulakos, 2000]



$$RC_r(\mathbf{z}, \tilde{\mathbf{z}}) = \frac{1}{N} \sum_i \left(\min_{j / (q_i - q_j)^2 < r^2} |v_i - \tilde{v}_j| \right)^2$$

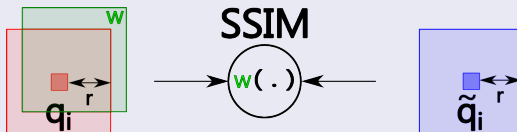
Euclidean Distance-based Measures



Cosine Angle Distance-based Measures

- μ_z (resp. $\mu_{\tilde{z}}$) the mean of v_i (resp. \tilde{v}_i) on z (resp. \tilde{z})
- σ_z (resp. $\sigma_{\tilde{z}}$) the standard deviation of v_i (resp. \tilde{v}_i)
- $\sigma_{z\tilde{z}}$ the covariance of z and \tilde{z}

Structural Similarity Measure [Wang et al., 2004]

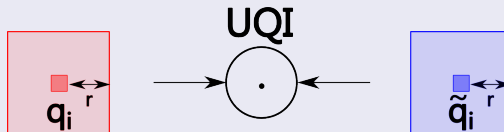


$$\begin{aligned}
 \text{SSIM}(\mathbf{z}, \tilde{\mathbf{z}}) &= l(\mathbf{z}, \tilde{\mathbf{z}}) \cdot c(\mathbf{z}, \tilde{\mathbf{z}}) \cdot s(\mathbf{z}, \tilde{\mathbf{z}}) \\
 &= \frac{2\mu_z\mu_{\tilde{z}} + \alpha}{\mu_z^2 + \mu_{\tilde{z}}^2 + \alpha} \cdot \frac{2\sigma_z\sigma_{\tilde{z}} + \beta}{\sigma_z^2 + \sigma_{\tilde{z}}^2 + \beta} \cdot \frac{\sigma_{z\tilde{z}} + \gamma}{\sigma_z\sigma_{\tilde{z}} + \gamma}
 \end{aligned}$$

Cosine Angle Distance-based Measures

- μ_z (resp. $\mu_{\tilde{z}}$) the mean of v_i (resp. \tilde{v}_i) on z (resp. \tilde{z})
- σ_z (resp. $\sigma_{\tilde{z}}$) the standard deviation of v_i (resp. \tilde{v}_i)
- $\sigma_{z\tilde{z}}$ the covariance of z and \tilde{z}

Universal Quality Image [Z. Wang and Bovik, 2002]

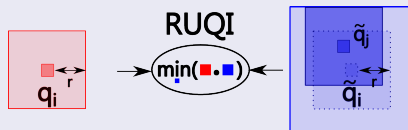


$$UQI(\mathbf{z}, \tilde{\mathbf{z}}) = \frac{4\sigma_{z\tilde{z}} \mu_z \mu_{\tilde{z}}}{(\sigma_z^2 + \sigma_{\tilde{z}}^2) [\mu_z^2 + \mu_{\tilde{z}}^2]}$$

Cosine Angle Distance-based Measures

- μ_z (resp. $\mu_{\tilde{z}}$) the mean of v_i (resp. \tilde{v}_i) on z (resp. \tilde{z})
- σ_z (resp. $\sigma_{\tilde{z}}$) the standard deviation of v_i (resp. \tilde{v}_i)
- $\sigma_{z\tilde{z}}$ the covariance of z and \tilde{z}

RUQI (Proposed measure)



$$\text{RUQI}(\mathbf{z}, \tilde{\mathbf{z}}) = \frac{1}{N} \sum_i \left(\max_{j / (q_i - q_j)^2 < r^2} (\text{UQI}(\xi_i, \tilde{\xi}_j)) \right)$$

Cosine Angle Distance-based Measures

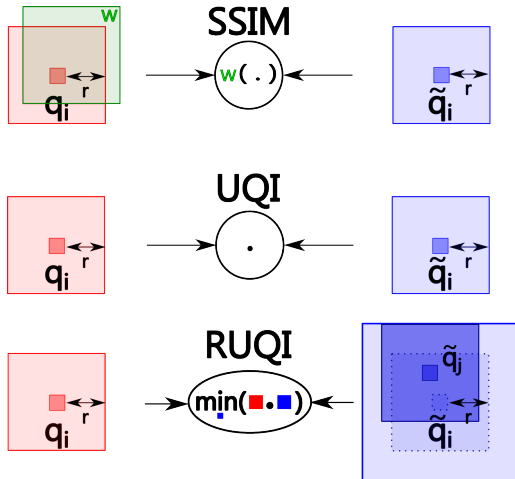
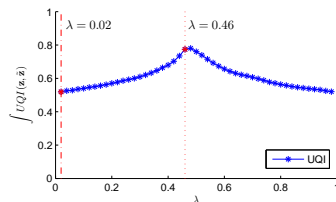
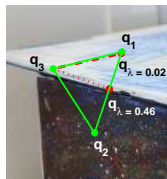


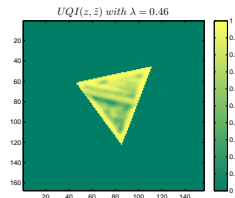
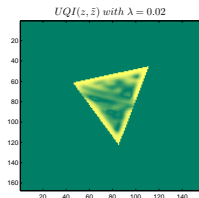
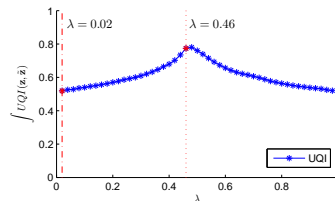
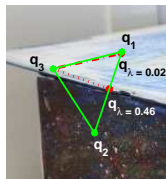
Table of contents

- 1 State-of-the-Art
- 2 Photo-Consistency Measures
- 3 IQA Evaluation Protocol**
- 4 Overview

IQA Protocol Evaluation



IQA Protocol Evaluation



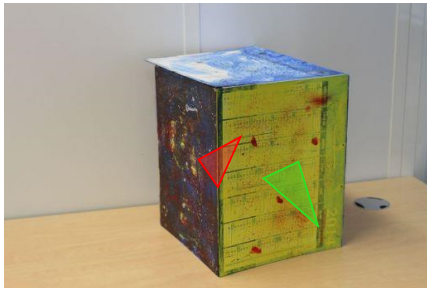
Non-planar triangle: Variation of IQA with different λ

Algorithm

- ➊ Estimation of right value λ^*
- ➋ Estimation of homographies
- ➌ For each $\lambda \in [0, 1]$
 - ➊ Estimation of the warped image depending on λ
 - ➋ Computation of the IQA value
- ➍ Classification in P/NP region based on the IQA value

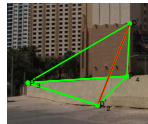
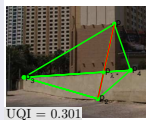
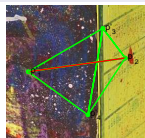
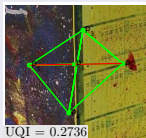
Experiment

Input data - Real data with controlled and uncontrolled lighting
Tests - 6 measures on 87 triangles (58% NP)

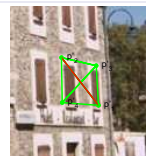
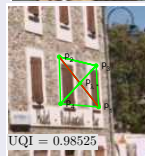
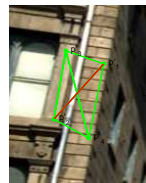
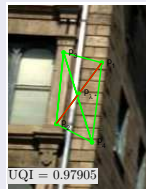


Results (1)

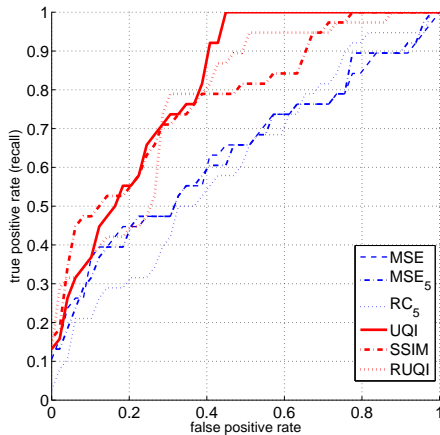
Non-planar zones



Planar zones

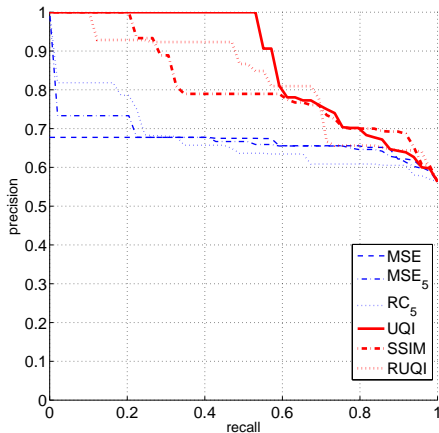


Results (2)



Receiver Operator Characteristic (ROC) curve

Results (3)



Precision-Recall (PR) curve

Table of contents

- 1 State-of-the-Art
- 2 Photo-Consistency Measures
- 3 IQA Evaluation Protocol
- 4 Overview**

Overview

Contributions

- IQA protocol evaluation for P/NP classification
- 'SSIM' more efficient than 'MSE'
- UQI overcomes all measures

Future work

- IQA integration in SP constructor
- Cut non-planar zone

References I



Felzenszwalb, P. and Huttenlocher, D. (2004).
Efficient graph-based image segmentation.
In IJCV.



Gallup, D., Frahm, J.-M., and Pollefeys, M. (2010).
Piecewise planar and non-planar stereo for urban scene reconstruction.
In IEEE CVPR.



Hoiem, D., Efros, A., and Herbert, M. (2008).
Closing the loop on scene interpretation.
In IEEE CVPR.



Kutulakos, K. (2000).
Approximate n-view stereo.
In ECCV.



Toldo, R. and Fusiello, A. (2010).
Photo-consistent planar patches from unstructured cloud of points.
In ECCV, pages 589–602.



Wang, Z., Bovik, A., Sheikh, H., and Simoncelli, E. (2004).
Image quality assessment: From error visibility to structural similarity.
In IEEE TRANSACTIONS ON IMAGE PROCESSING.



Z. Wang, Z. and Bovik, A. (2002).
A universal image quality index.
In IEEE Signal Processing Letters.

Test \ GT	1	0	
1	TP	FP	Pr
0	FN	TN	NPr
	R	NR	
		FPR	

Binary classification evaluation